

On $LR(k)$ -parsers of polynomial size

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Abstract.

Usually, a parser for an $LR(k)$ -grammar G is a deterministic pushdown transducer which produces backwards the unique rightmost derivation for a given input string $x \in L(G)$. The best known upper bound for the size of such a parser is $O(2^{|\Sigma|^{k+1}})$ where $|G|$ and $|\Sigma|$ are the sizes of the grammar G and the terminal alphabet Σ , respectively. If we add to a parser the possibility to manipulate a directed graph of size $O(|G|n)$ where n is the length of the input then we obtain an extended parser. The graph is used for an efficient parallel simulation of all potential leftmost derivations of the current right sentential form such that the unique rightmost derivation of the input can be computed. Given an arbitrary $LR(k)$ -grammar G , we show how to construct an extended parser of $O(|G| + \#LA|N|2^k k \log k)$ size where $|N|$ is the number of nonterminal symbols and $\#LA$ is the number of possible lookaheads with respect to the grammar G . As the usual parser, this extended parser uses only tables as data structure. Using some ingenious data structures and increasing the parsing time by a small constant factor, the size of the extended parser can be reduced to $O(|G| + \#LA|N|k^2)$. The parsing time is $O(ld(input) + k|G|n)$ where $ld(input)$ is the length of the derivation of the input. Moreover, we have constructed a one pass parser.

1 Introduction

Efficient implementations of parsers for context-free grammars play an important role with respect to the construction of compilers. Since practical algorithms for general context-free analysis need cubic time, during the sixties subclasses of the context-free grammars having linear time parsers were defined. The most important such subclasses are the $LR(k)$ - and the $LL(k)$ -grammars. But the size of linear $LR(k)$ - and $LL(k)$ -parsers might be exponential in the size of the underlying grammar. Indeed, Ukkonen [11] has constructed families of $LR(k)$ - and $LL(k)$ -grammars having only parsers of exponential size. The reason is that parsers read the input from left to right in one pass without backtrack and treat always the only possible derivation which can depend on the prefix of the input derived so far. Hence, the state of the parser has to include all necessary information about the prefix of the input read so far. Instead of the treatment of the only possible derivation one can consider a set of potential derivations which always contains the correct derivation in parallel. Hence, the following question

arises: Is it possible to simulate an accurate set of derivations in parallel such that the correct derivation will be computed, the needed time remains linear and the modified parser uses on the input one pass without backtrack and has only polynomial size?

In [3] for $LL(k)$ -grammars the following positive answer to this question is given: If we add to a parser the possibility to manipulate a constant number of pointers which point to positions within the constructed part of the leftmost derivation and to change the output in such positions, we obtain an extended parser for an $LL(k)$ -grammar G . Given an arbitrary $LL(k)$ -grammar $G = (V, \Sigma, P, S)$, it is shown how to construct an extended parser of size $O(|G| + k|N||\Sigma|^k)$ manipulating at most k^2 pointers. The parsing time is bounded by $O(n)$ where n is the length of the input. In the case of $LR(k)$ -grammars the situation is a little bit more complicated. The parser has to take into account all possible derivations of the current right sentential form. Hence, the state of the parser has to include all necessary information with respect to all possible derivations of the current rightmost sentential form from the start symbol. Instead of storing the whole needed information into the state the parser can treat simultaneously all potential leftmost derivations and also backwards the rightmost derivation which has to be computed. Hence, with respect to $LR(k)$ -grammars, the following question arises: For the computation of the unique rightmost derivation, is it possible to simulate all possible leftmost derivations and also backwards the rightmost derivation such that the rightmost derivation will be computed, the needed time remains linear, the modified parser uses on the input one pass without backtrack and has only polynomial size?

We will consider arbitrary $LR(k)$ -grammars. The usual parser for an $LR(k)$ -grammar $G = (V, \Sigma, P, S)$ is the so-called *canonical $LR(k)$ -parser*. The best known upper bound for its size is $O(2^{|G|}|\Sigma|^{k+k \log |\Sigma| + \log |G|})$ [9]. Hence, DeRemer [5] has defined two subclasses of the class of $LR(k)$ -grammars, the $SLR(k)$ -grammars and the $LALR(k)$ -grammars. Both classes allow smaller canonical LR -parsers. But the size of these parsers can still be $O(2^{|G|})$ [9]. Hence, the question posed above remains interesting for $SLR(k)$ - and $LALR(k)$ -grammars, too. We will give a positive answer to this question for arbitrary $LR(k)$ -grammars. We assume that the reader is familiar with the elementary theory of $LR(k)$ -parsing as written in standard text books (see e.g. [1, 2, 4, 7, 8, 12]). First, we will review the notations used in the subsequence.

2 Basic notations

A *context-free grammar (cfg)* G is a four-tuple (V, Σ, P, S) where V is a finite, nonempty set of symbols called the *total vocabulary*, $\Sigma \subset V$ is a finite set of *terminal symbols*, $N := V \setminus \Sigma$ is the set of *nonterminal symbols* (or *variables*), P is a finite set of *productions*, and $S \in N$ is the *start symbol*. The productions are of the form $A \rightarrow \alpha$, where $A \in N$ and $\alpha \in V^*$. α is called an *alternative* of A . $L(G)$ denotes the *context-free language* generated by G . The *size* $|G|$ of the cfg G is defined by $|G| := \sum_{A \rightarrow \alpha \in P} lg(A\alpha)$, where $lg(A\alpha)$ is the length of

the string $A\alpha$. As usual, ε denotes the empty word. A derivation is *rightmost* if at each step a production is applied to the rightmost variable. A sentential form within a rightmost derivation starting in S is called *right sentential form*. *Leftmost* derivation and *left sentential form* are defined analogously. A context-free grammar G is *ambiguous* if there exists $x \in L(G)$ such that there are two distinct leftmost derivations of x from the start symbol S . A context-free grammar $G = (V, \Sigma, P, S)$ is *reduced* if $P = \emptyset$ or, for each $A \in V$, $S \xRightarrow{*} \alpha A \beta \xRightarrow{*} w$ for some $\alpha, \beta \in V^*$, $w \in \Sigma^*$. In the subsequence, all derivations will be rightmost.

A *pushdown automaton* M is a seven-tuple $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$, where Q is a finite, nonempty set of *states*, Σ is a finite, nonempty set of *input symbols*, Γ is a finite, nonempty set of *pushdown symbols*, $q_0 \in Q$ is the *initial state*, $Z_0 \in \Gamma$ is the *start symbol* of the pushdown store, $F \subseteq Q$ is the set of *final states*, and δ is a mapping from $Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma$ to finite subsets of $Q \times \Gamma^*$. A pushdown automaton is *deterministic* if for each $q \in Q$ and $Z \in \Gamma$ either $\delta(q, a, Z)$ contains at most one element for each $a \in \Sigma$ and $\delta(q, \varepsilon, Z) = \emptyset$ or $\delta(q, a, Z) = \emptyset$ for all $a \in \Sigma$ and $\delta(q, \varepsilon, Z)$ contains at most one element. A deterministic pushdown transducer is a deterministic pushdown automaton with the additional property to produce an output. More formally, a *deterministic pushdown transducer* is an eight-tuple $(Q, \Sigma, \Gamma, \Delta, \delta, q_0, Z_0, F)$, where all symbols have the same meaning as for a pushdown automaton except that Δ is a finite *output alphabet* and δ is now a mapping $\delta : Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \mapsto Q \times \Gamma^* \times \Delta^*$.

For a context-free grammar $G = (V, \Sigma, P, S)$, an integer k , and $\alpha \in V^*$ the set $FIRST_k(\alpha)$ contains all terminal strings of length $\leq k$ and all prefixes of length k of terminal strings which can be derived from α in G . More formally,

$$FIRST_k(\alpha) := \{x \in \Sigma^* \mid \alpha \xRightarrow{*} xy, y \in \Sigma^+ \text{ and } |x| = k \text{ or } y = \varepsilon \text{ and } |x| \leq k\}.$$

We will use efficient data structures for the representation of $FIRST_k$ -sets. A usual way to represent a finite set of strings is the use of a trie. Let Σ be a finite alphabet of size l . A *trie* with respect to Σ is a directed tree $T = (V, E)$ where each node $v \in V$ has outdegree $\leq l$. The outgoing edges of a node v are marked by pairwise distinct elements of the alphabet Σ . The node v represents the string $s(v)$ which is obtained by the concatenation of the edge markings on the unique path from the root r of T to v . An efficient algorithm without the use of fixed-point iteration for the computation of all $FIRST_k$ -sets can be found in [2].

Let $G = (V, \Sigma, P, S)$ be a reduced, context-free grammar and $k \geq 0$ be an integer. We say that G is $LR(k)$ if

1. $S \xRightarrow{*} \alpha A w \Rightarrow \alpha \beta w$,
2. $S \xRightarrow{*} \gamma B x \Rightarrow \alpha \beta y$, and
3. $FIRST_k(w) = FIRST_k(y)$

imply $\alpha = \gamma$, $A = B$, and $x = y$.

In the next three sections, the necessary background is given. Section 3 describes the canonical $LR(k)$ -parser. Section 4 presents the pushdown automaton M_G designed for an arbitrary context-free grammar G . Its efficient simulation is

described in Section 5. Section 6 combines the canonical $LR(k)$ -parser and the efficient simulation of M_G for an arbitrary $LR(k)$ -grammar G obtaining the extended $LR(k)$ -parser for G . In Section 7, we describe an efficient implementation of the $LR(k)$ -parser

3 The canonical $LR(k)$ -parser

For the construction of a parser for an $LR(k)$ -grammar G the following notations are useful: Let $S \xRightarrow{*} \alpha Aw \Rightarrow \alpha \beta w$ be a rightmost derivation in G . A prefix γ of $\alpha \beta$ is called *viable prefix* of G . A production in P with a dot on its right side is an *item*. More exactly, let $p = X \rightarrow X_1 X_2 \dots X_{n_p} \in P$. Then $[p, i]$, $0 \leq i \leq n_p$ is an *item* which is represented by $[X \rightarrow X_1 X_2 \dots \dot{X}_i X_{i+1} \dots X_{n_p}]$. If $p = X \rightarrow \varepsilon$ then we simply write $[X \rightarrow \cdot]$. If we add to an item a terminal string of length $\leq k$ then we obtain an $LR(k)$ -item. More formally, $[A \rightarrow \beta_1 \cdot \beta_2, u]$ where $A \rightarrow \beta_1 \beta_2 \in P$ and $u \in \Sigma^{\leq k}$ is an $LR(k)$ -item. An $LR(k)$ -item $[A \rightarrow \beta_1 \cdot \beta_2, u]$ is *valid* for $\alpha \beta_1 \in V^*$ if there is a derivation $S \xRightarrow{*} \alpha Aw \Rightarrow \alpha \beta_1 \beta_2 w$ with $u \in FIRST_k(\beta_2 w)$. Note that by definition, an $LR(k)$ -item can only be valid for a viable prefix of G .

The canonical LR -parser is a *shift-reduce parser*. A shift-reduce parser is a pushdown automaton which constructs a rightmost derivation backwards. We will give an informal description of such a pushdown automaton. Let $S \Rightarrow \alpha_0 \Rightarrow \alpha_1 \Rightarrow \dots \Rightarrow \alpha_{m-1} \Rightarrow \alpha_m = x$ be a rightmost derivation of x from S . The shift-reduce parser starts with the right sentential form $\alpha_m := x$ as input and constructs successively the right sentential forms $\alpha_{m-1}, \alpha_{m-2}, \dots, \alpha_1, \alpha_0, S$. The current right sentential form will always be the concatenation of the content of the pushdown store from the bottom to the top and the unread suffix of the input. At the beginning, the pushdown store is empty. Let y be the unexpanded input and $\alpha_i = \gamma y$ be the current right sentential form. Then γ is the current content of the pushdown store where the last symbol of γ is the uppermost symbol of the pushdown store. Our goal is to construct the right sentential form α_{i-1} from α_i .

If $\alpha_i = \gamma_1 \gamma_2 y$ and $\alpha_{i-1} = \gamma_1 A y$ then the alternative γ_2 of the variable A expanded in the current step is on the top of the stack. If $\alpha_i = \gamma_1 \gamma_2 y_1 y_2$ and $\alpha_{i-1} = \gamma_1 A y_2$ then a portion of the alternative of A is prefix of the unexpanded input y . The goal of the shift-reduce parser is to take care that the alternative of the variable A expanded in α_{i-1} is on the top of the stack. If the alternative of A is on the top of the stack then the shift-reduce parser replaces this alternative by A . For doing this, the shift-reduce parser uses the following operations:

1. The next input symbol is read and shifted on the top of the pushdown store.
2. The shift-reduce parser identifies that the alternative of A is on the top of the stack and replaces this alternative by A . Therefore, a reduction is performed.

In each step, the shift-reduce parser can perform any of the two operations. In general, the shift-reduce parser is nondeterministic. $LR(k)$ -grammars allow to

make the shift-reduce parser deterministically. Moreover, the set of the $LR(k)$ -items valid for the current content of the stack contains always the information which is sufficient to decide uniquely the next step of the shift-reduce parser. For the proof of this central theorem we need the following lemma which gives a more specific characterization of context-free grammars which are not $LR(k)$.

Lemma 1 *Let $k \geq 0$ be an integer and $G = (V, \Sigma, P, S)$ be a reduced cfg which is not $LR(k)$. Then there exists derivations*

1. $S \xRightarrow{*} \alpha Aw \Rightarrow \alpha \beta w$ and
2. $S \xRightarrow{*} \gamma Bx \Rightarrow \gamma \delta x = \alpha \beta y$

where $FIRST_k(w) = FIRST_k(y)$ and $|\gamma \delta| \geq |\alpha \beta|$ but $\alpha Ay \neq \gamma Bx$.

The proof can be found in [1] (proof of Lemma 5.2 at page 382).

Let γy be the current right sentential form; i.e., γ is the current content of the stack and y is the unread suffix of the input. Let $u := FIRST_k(y)$ be the current *lookahead*. Let $[A \rightarrow \beta_1 \cdot \beta_2, v]$ be an $LR(k)$ -item which is valid for γ . Then β_1 is a suffix of γ . If $\beta_2 = \varepsilon$ then we have $v = u$ and the $LR(k)$ -item $[A \rightarrow \beta_1 \cdot, u]$ corresponds to a reduction which can be performed by the shift-reduce parser. If $\beta_2 \in \Sigma V^*$ and $u \in FIRST_k(\beta_2 v)$ then the $LR(k)$ -item $[A \rightarrow \beta_1 \cdot \beta_2, v]$ corresponds to a reading which can be performed by the shift-reduce parser. The following theorem tells us that the set of all $LR(k)$ -items valid for γ corresponds to at most one step which can be performed by the shift-reduce parser. Note that Theorem 1 is a weaker version of Theorem 5.9 in [1] which uses the so-called ε -free first function $EFF_k(\alpha)$. Since the weaker version suffices such that the ε -free first function is not needed, we present the theorem and the proof here.

Theorem 1 *Let $k \geq 0$ be an integer and $G = (V, \Sigma, P, S)$ be a context-free grammar. G is $LR(k)$ if and only if for all $u \in \Sigma^{\leq k}$ and all $\alpha \beta \in V^*$ the following property is fulfilled: If an $LR(k)$ -item $[A \rightarrow \beta \cdot, u]$ is valid for $\alpha \beta$ then there exists no other $LR(k)$ -item $[C \rightarrow \beta_1 \cdot \beta_2, v]$ valid for $\alpha \beta$ with $\beta_2 \in \Sigma V^* \cup \{\varepsilon\}$ and $u \in FIRST_k(\beta_2 v)$.*

Proof: Assume that G is an $LR(k)$ -grammar. Let $[A \rightarrow \beta \cdot, u]$ and $[C \rightarrow \beta_1 \cdot \beta_2, v]$ with $\beta_2 \in \Sigma V^* \cup \{\varepsilon\}$ and $u \in FIRST_k(\beta_2 v)$ be two distinct $LR(k)$ -items valid for $\alpha \beta$. Then there are derivations

$$\begin{aligned} S &\xRightarrow{*} \alpha Aw \Rightarrow \alpha \beta w && \text{and} \\ S &\xRightarrow{*} \alpha_1 Cx \Rightarrow \alpha_1 \beta_1 \beta_2 x \end{aligned}$$

where $u = FIRST_k(w)$ and $v = FIRST_k(x)$. We have to prove that G cannot be $LR(k)$. With respect to β_2 three cases are possible:

Case 1: $\beta_2 = \varepsilon$.

Then we have $u = v$. Hence, both derivations look as follows:

$$\begin{aligned} S &\xRightarrow{*} \alpha Aw \Rightarrow \alpha \beta w && \text{and} \\ S &\xRightarrow{*} \alpha_1 Cx \Rightarrow \alpha_1 \beta_1 x = \alpha \beta x, \end{aligned}$$

where $FIRST_k(w) = FIRST_k(x) = u$. Since both $LR(k)$ -items are distinct, we obtain $A \neq C$ or $\beta \neq \beta_1$. Note that $\beta \neq \beta_1$ implies $\alpha \neq \alpha_1$. In both cases, we obtain a contradiction to the definition of $LR(k)$ -grammers.

Case 2: $\beta_2 = z$ where $z \in \Sigma^+$.

Then both derivations look as follows:

$$\begin{aligned} S &\xrightarrow{*} \alpha Aw \Rightarrow \alpha\beta w && \text{and} \\ S &\xrightarrow{*} \alpha_1 Cx \Rightarrow \alpha_1\beta_1 zx, \end{aligned}$$

where $\alpha\beta = \alpha_1\beta_1$ and $FIRST_k(w) = FIRST_k(zx) = u$. $z \in \Sigma^+$ implies that $x \neq zx$. Hence, by the definition of $LR(k)$ -grammers, G cannot be $LR(k)$.

Case 3: $\beta_2 = a\beta'_2$ where $a \in \Sigma$ and $\beta'_2 \in V^*NV^*$.

Then there are $u_1, u_2, u_3 \in \Sigma^*$ such that $\beta_2 = a\beta'_2 \xrightarrow{*} au_1Bu_3 \Rightarrow au_1u_2u_3$ with $FIRST_k(au_1u_2u_3x) = u$. Therefore, both derivations look as follows:

$$\begin{aligned} S &\xrightarrow{*} \alpha Aw \Rightarrow \alpha\beta w && \text{and} \\ S &\xrightarrow{*} \alpha_1 Cx \Rightarrow \alpha_1\beta_1 a\beta'_2 x \xrightarrow{*} \alpha_1\beta_1 au_1Bu_3x \Rightarrow \alpha_1\beta_1 au_1u_2u_3x \end{aligned}$$

where $\alpha\beta = \alpha_1\beta_1$. Applying the definition of $LR(k)$ -grammers to the derivations

$$\begin{aligned} S &\xrightarrow{*} \alpha Aw \Rightarrow \alpha\beta w && \text{and} \\ S &\xrightarrow{*} \alpha_1\beta_1 au_1Bu_3x \Rightarrow \alpha_1\beta_1 au_1u_2u_3x, \end{aligned}$$

we obtain $\alpha = \alpha_1\beta_1 au_1$. Since $\alpha\beta = \alpha_1\beta_1$ and $a \in \Sigma$ this is impossible. Hence, G cannot be $LR(k)$.

For the proof of the other direction assume that G is not $LR(k)$. Then Lemma 1 implies that there are two derivations

$$\begin{aligned} S &\xrightarrow{*} \alpha Aw \Rightarrow \alpha\beta w && \text{and} \\ S &\xrightarrow{*} \gamma Cx \Rightarrow \gamma\delta x = \alpha\beta y \end{aligned}$$

with $u := FIRST_k(w) = FIRST_k(y)$, $|\gamma\delta| \geq |\alpha\beta|$ and $\alpha Ay \neq \gamma Cx$. This implies that the $LR(k)$ -item $[A \rightarrow \beta \cdot, u]$ is valid for $\alpha\beta$. Hence, it remains to construct a further $LR(k)$ -item $[C \rightarrow \beta_1 \cdot \beta_2, v]$ with $\beta_2 \in \Sigma V^* \cup \{\varepsilon\}$ and $u \in FIRST_k(\beta_2 v)$ which is valid for $\alpha\beta$.

Since $|\gamma\delta| \geq |\alpha\beta|$ and $\gamma\delta x = \alpha\beta y$ there holds $\gamma\delta = \alpha\beta z$ for a $z \in \Sigma^*$. Two cases are possible: z is a suffix of δ or δ is a suffix of z .

If $\delta = \delta'z$ for a $\delta' \in V^*$ then $y = zx$ implies that the $LR(k)$ -item $[C \rightarrow \delta' \cdot z, v]$ with $v = FIRST_k(x)$ is valid for $\alpha\beta$. Assume that $[C \rightarrow \delta' \cdot z, v] = [A \rightarrow \beta \cdot, u]$. Then $A = C$, $\beta = \delta'$, $z = \varepsilon$ and $u = v$. This implies also $\beta = \delta$ and therefore $\alpha = \gamma$ and $x = y$. But this is a contradiction to $\alpha Ay \neq \gamma Cx$. Hence, $[C \rightarrow \delta' \cdot z, v] \neq [A \rightarrow \beta \cdot, u]$.

If $z = z'\delta$ for a $z' \in \Sigma^+$ then we consider the rightmost derivation $S \Rightarrow_{rm}^* \alpha\beta z' Cx$. Let $\alpha_1 B y_1$ be the last right sentential form of this derivation with $y_1 \in \Sigma^*$, $B \in N$ and $|\alpha_1 B| \leq |\alpha\beta| + 1$. Note that $|S| = 1$ implies that this right sentential form exists. Hence, we can write the derivation of $\alpha\beta y$ from S in the following form:

$$S \xRightarrow{*} \alpha_1 B y_1 \Rightarrow \alpha_1 \beta_1 \beta_2 y_1 \xRightarrow{*} \alpha_1 \beta_1 y$$

where $\alpha_1 \beta_1 = \alpha \beta$. By the choice of the right sentential form $\alpha_1 B y_1$ there holds $|\alpha_1| \leq |\alpha \beta|$ and $\beta_2 \in \Sigma V^*$. Hence, the $LR(k)$ -item $[B \rightarrow \beta_1 \cdot \beta_2, v]$ where $v = FIRST_k(y_1)$ is valid for $\alpha \beta$. $FIRST_k(y) = u$ implies $u \in FIRST_k(\beta_2 v)$. Since $\beta_2 \in \Sigma V^*$ the items $[A \rightarrow \beta \cdot, u]$ and $[B \rightarrow \beta_1 \cdot \beta_2, v]$ have to be distinct. ■

With respect to the shift-reduce parser, the theorem has the following implication: If during the construction of the rightmost derivation an $LR(k)$ -item $[A \rightarrow \beta \cdot, u]$ is valid for the current content γ of the stack and u is the current lookahead then β is on the top of the pushdown store and the reduction corresponding to the production $A \rightarrow \beta$ is the only applicable step of the shift-reduce parser. If an $LR(k)$ -item $[C \rightarrow \beta_1 \cdot \beta_2, v]$ with $\beta_2 \in \Sigma V^*$ is valid for the current content of the stack and the current lookahead u is in $FIRST_k(\beta_2 v)$ then the reading which corresponds to the first symbol of u is the only applicable step of the shift-reduce parser.

4 The pushdown automaton M_G

For the parallel simulation of all potential leftmost derivations we need the following pushdown automaton: Given any context-free grammar $G = (V, \Sigma, P, S)$, we will construct a pushdown automaton M_G with $L(M_G) = L(G)$ which produces a leftmost derivation. For a production $p \in P$, n_p denotes the length of the right side of p . Let $H_G = \{[p, i] \mid p \in P, 0 \leq i \leq n_p\}$ be the set of all items of G . Then $M_G = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ is defined by

$$\begin{aligned} Q &= H_G \cup \{[S' \rightarrow \cdot S], [S' \rightarrow S \cdot]\}, \\ q_0 &= [S' \rightarrow \cdot S], F = \{[S' \rightarrow S \cdot]\}, \\ \Gamma &= Q \cup \{\perp\}, Z_0 = \perp, \text{ and} \\ \delta &: Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \mapsto 2^{Q \times \Gamma^*}. \end{aligned}$$

δ will be defined such that M_G simulates a leftmost derivation. With respect to δ , we distinguish three types of steps.

(E) *expansion*

$$\delta([X \rightarrow \beta \cdot A\gamma], \varepsilon, Z) = \{([A \rightarrow \alpha \cdot], [X \rightarrow \beta \cdot A\gamma]Z) \mid A \rightarrow \alpha \in P\}.$$

The leftmost variable in the left sentential form is replaced by one of its alternatives. The pushdown store is expanded.

(C) *reading*

$$\delta([X \rightarrow \varphi \cdot a\psi], a, Z) = \{([X \rightarrow \varphi a \cdot \psi], Z)\}.$$

The next input symbol is read.

(R) *reduction*

$$\delta([X \rightarrow \alpha \cdot], \varepsilon, [W \rightarrow \mu \cdot X\nu]) = \{([W \rightarrow \mu X \cdot \nu], \varepsilon)\}.$$

The whole alternative α is derived from X . Hence, the dot can be moved beyond X and the corresponding item can be removed from the pushdown store getting the new state. Therefore, the pushdown store is reduced.

The basis for the construction of a polynomial size extended $LR(k)$ -parser is an efficient deterministic simulation of M_G . This simulation will be described in the next section.

5 The deterministic simulation of M_G

Let $G = (V, \Sigma, P, S)$ be a reduced context-free grammar. Our goal is to develop a deterministic simulation of the pushdown automaton M_G defined in the previous section. The algorithm which we will develop looks much like Earley's algorithm [6]. But in contrast to Earley's algorithm, the algorithm maintains the structure of the computation of the underlying pushdown automaton M_G . For the construction of the extended $LR(k)$ -parser, this structure of the computation of M_G is needed. Next we will describe the simulation of M_G . Tomita [10] has developed a similar approach the "graph-structured stack" which is restricted to non-cyclic grammars such that the graphs remain to be acyclic. Next we will describe the simulation of M_G .

If we write the current state of M_G always on the top of the stack then we have only to solve the problem of the deterministic simulation of the stack. The idea is to simulate all possible contents of the stack in parallel. Since an exponential number of different stacks are possible at the same time, the direct simulation of all stacks in parallel cannot be efficient. Observe that the grammar G and therefore the pushdown automaton M_G have a fixed size. Hence, at any time, at most a constant number of distinct items can be on the top of all stacks. Hence, there are only a constant number of possibilities to modify eventually an exponential number of different stacks. This observation suggests the following method:

We realize all stacks simultaneously by a directed graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$. Each node of the graph is marked by an item. We identify each node with its item. The graph contains exactly one node with indegree zero. This node is marked by the item $[S' \rightarrow \cdot S]$. We call this node the *start node* and nodes with outdegree zero *end nodes*. Everytime, we have a bijection of the paths from the start node to an end node and the possible contents of the stack. The algorithm separates into *phases*. During each phase, we treat all end nodes simultaneously. For doing this, we have the difficulty that with respect to different end nodes the kind of steps which have to be performed might be different; i.e., some end nodes have to be expanded, other end nodes have to be reduced, and some end nodes need a reading. Hence, it can be the case that with respect to different end nodes the unexpanded input might be different. For the solution of this difficulty, we synchronize the computation using the following rules:

1. As long as there is an end node of the form $[A \rightarrow \alpha_1 \cdot B\alpha_2]$, $B \in N$ perform an expansion with respect to this end node.
2. If all end nodes are of the form $[A \rightarrow \alpha_1 \cdot \alpha_2]$, $\alpha_2 \in \Sigma V^* \cup \{\varepsilon\}$ then perform a reduction with respect to all end nodes with $\alpha_2 = \varepsilon$.
3. If all end nodes are of the form $[A \rightarrow \alpha_1 \cdot a\alpha_2]$, $a \in \Sigma$ then perform a reading with respect to all end nodes.

At the end of each phase exactly one input symbol has been read. Hence, we have n phases where n is the length of the input. We number these phases from 1 to n . Each phase separates into two subphases. During the first subphase, we perform

all possible expansions and reductions. An end node of the form $[A \rightarrow \alpha_1 \cdot \alpha_2]$ with $\alpha_2 \in NV^*$ is called *expansible*, with $\alpha_2 \in \Sigma V^*$ is called *readable*, and with $\alpha_2 = \varepsilon$ is called *reducible*.

The first subphase is separated into rounds. In the first round, we perform as long as possible expansions. We call such a round *expansion step*. The same node is inserted only once. Instead of inserting the same node again, an edge pointing to the node inserted before is created. Since the alternative of an expanded nonterminal can be in NV^* , possibly we have to expand the new node again. Maybe, some cycles are constructed; e.g., the following chain of expansions would produce a cycle:

$$[A \rightarrow \alpha_1 \cdot B\alpha_2], [B \rightarrow \cdot C\beta_1], [C \rightarrow \cdot B\beta_2], [B \rightarrow \cdot C\beta_1].$$

In the second round, we perform all possible reductions. Such a round is called *reduction step*. According to the reductions, maybe some further expansions are possible. These are performed during a third round. If the alternative of the expanded variable is ε then this new end node is reducible and causes a reduction. All these reductions are performed in the next round a.s.o. New nodes are indexed by the number of the current phase. A reduction step is performed as follows: We remove all reducible nodes from the graph. Two cases with respect to a direct predecessor u of a removed node can arise:

1. All its successors are reducible and will be removed. Then u is of Type 1.
2. u has successors which will be not removed. Then u is of Type 2.

If u is of Type 1 then the dot of the item u will be moved by one position to the right. The index of u is changed to the number of the current phase. If u is of Type 2 then we copy the node u and all ingoing edges of u and move the dot of the copy u' of u by one position to the right. We index u' by the number of the current phase. Possibly, after moving the dot in u or in u' , the node u or u' becomes reducible, expansible, or readable.

After the first subphase, all end nodes have a terminal symbol behind its dot. During the second subphase, we perform the reading step. Assume that the $(i + 1)$ th input symbol a_{i+1} is the first unread input symbol. End nodes where the terminal symbol behind the dot is unequal a_{i+1} cannot lead to an accepting computation of the pushdown automaton M_G . Hence, they can be removed from the graph. Nodes where all successors are removed can also be deleted. In end nodes with the first symbol behind the dot is a_{i+1} , we move the dot one position to the right and change the index of the current item to $i + 1$. Altogether, we obtain the following algorithm:

Algorithm SIMULATION(M_G)

Input: A reduced cfg $G = (V, \Sigma, P, S)$ and $w = a_1 a_2 \dots a_n \in \Sigma^+$.

Output: “accept” if $w \in L(G)$ and “error” otherwise.

Method:

- (1) Initialize $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ by $\mathcal{V} := \{[S' \rightarrow \cdot S]_0\}$ and $\mathcal{E} := \emptyset$;
 $H := \{[S' \rightarrow \cdot S]_0\}$;

```

K := ∅; R := ∅; Pr := ∅;
exp := 1; red := 0;
i := 0;
(2) while i ≤ n
do
  (ER) while exp = 1
  do
    while H ≠ ∅
    do
      Choose any  $[A \rightarrow \alpha_1 \cdot B\alpha_2]_i \in H$ ;
      H := H \  $\{[A \rightarrow \alpha_1 \cdot B\alpha_2]_i\}$ ;
      K := K ∪  $\{[A \rightarrow \alpha_1 \cdot B\alpha_2]_i\}$ ;
      for each alternative  $\beta$  of B
      do
        V := V ∪  $\{[B \rightarrow \cdot\beta]_i\}$ 
        E := E
          ∪  $\{([A \rightarrow \alpha_1 \cdot B\alpha_2]_i, [B \rightarrow \cdot\beta]_i)\}$ ;
        if  $\beta = \varepsilon$ 
        then
          R := R ∪  $\{[B \rightarrow \varepsilon \cdot]_i\}$ ; red := 1
        fi;
        if  $\beta \in NV^*$  and  $[B \rightarrow \cdot\beta]_i \notin K$ 
        then
          H := H ∪  $\{[B \rightarrow \cdot\beta]_i\}$ 
        fi
      od;
    od;
  exp := 0;
  while red = 1
  do
    while R ≠ ∅
    do
      Choose any  $[A \rightarrow \alpha \cdot]_i \in R$ ;
      R := R \  $\{[A \rightarrow \alpha \cdot]_i\}$ ;
      Pr := Pr ∪  $\{u \in \mathcal{V} \mid u \text{ is direct predecessor of } [A \rightarrow \alpha \cdot]_i\}$ ;
    od;
    red := 0;
    while Pr ≠ ∅
    do
      Choose any u ∈ Pr;
      Pr := Pr \  $\{u\}$ ;
      if u is of Type 1
      then
        move the dot in u one position
    od
  od

```

```

to the right;
change the index of  $u$  to  $i$ ;
if  $u$  is expansible
then
     $H := H \cup \{u\}$ ;  $exp := 1$ 
else
    if  $u$  is reducible
    then
         $R := R \cup \{u\}$ ;  $red := 1$ 
    fi
fi
else
    copy  $u$  with index  $i$  and all ingoing
    edges of  $u$ ;
    move the dot in  $u'$  one position
    to the right;
    if  $u'$  is expansible
    then
         $H := H \cup \{u'\}$ ;  $exp := 1$ 
    else
        if  $u'$  is reducible
        then
             $R := R \cup \{u'\}$ ;  $red := 1$ 
        fi
    fi
fi;
od
od
od;
(R) Delete all end nodes  $[A \rightarrow \alpha \cdot a\beta]_i$  with  $a \neq a_{i+1}$ ;
    As long as such nodes exists, delete nodes with the
    property that all successors are removed;
    Replace each end node  $[A \rightarrow \alpha \cdot a_{i+1}\beta]_i$  by the
    node  $[A \rightarrow \alpha a_{i+1} \cdot \beta]_{i+1}$  and modify  $H$  and  $R$ 
    as follows;
    if  $\beta \in NV^*$ 
    then
         $H := H \cup \{[A \rightarrow \alpha a_{i+1} \cdot \beta]_{i+1}\}$ ;  $exp := 1$ 
    fi;
    if  $\beta = \varepsilon$ 
    then
         $R := R \cup \{[A \rightarrow \alpha a_{i+1} \cdot ]_{i+1}\}$ ;  $red := 1$ 
    fi;
     $i := i + 1$ 
od;

```

(3) **if** $[S' \rightarrow S \cdot]_n \in V$
then
 output := “accept”
else
 output := “error”
fi.

Note that the graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ can contain some cycles. The index of an item is equal to the length of the already read input. This index will be helpful for understanding the simulation algorithm and can be omitted in any implementation of the algorithm. The correctness of the algorithm follows from the fact that after each performance of a phase there is a bijection between the paths from the start node to the end nodes and the possible contents of the stack. This can easily be proved by induction. It is also easy to prove that the algorithm $\text{SIMULATION}(M_G)$ uses $O(n^3)$ time and $O(n^2)$ space where n is the length of the input. If the context-free grammar G is unambiguous, the needed time reduces to $O(n^2)$.

6 The construction of the extended $LR(k)$ -parser

Let $k \geq 0$ be an integer and let $G = (V, \Sigma, P, S)$ be an arbitrary $LR(k)$ -grammar. The idea is to combine the concept of the shift-reduce parser and the deterministic simulation of the pushdown automaton M_G . This means that for the construction of the extended parser P_G we use M_G under regard of properties of $LR(k)$ -grammars. Just as for the construction of the canonical $LR(k)$ -parser, Theorem 1 is the key for the construction of the extended $LR(k)$ -parser. Note that Theorem 1 is a statement about valid $LR(k)$ -items for a viable prefix of G . Hence, we are interested in all maximal viable prefixes represented by the current graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ of the simulation algorithm of M_G . In the subsequence, we omit the indices of the items if they are not needed. Let $[A \rightarrow \alpha_1 \cdot \alpha_2]$ be an item. Then we call the portion α_1 left from the dot the *left side* of the item $[A \rightarrow \alpha_1 \cdot \alpha_2]$. Let P be any path from the start node to an end node in \mathcal{G} . Then the concatenation of the left sides of the items from the start node to the end node of P results in the maximal viable prefix $\text{pref}(P)$ with respect to P ; i.e., if

$$P = [S' \rightarrow \cdot S], [S \rightarrow \alpha_1 \cdot A_2 \beta_1], [A_2 \rightarrow \alpha_2 \cdot A_3 \beta_2], \dots, [A_t \rightarrow \alpha_t \cdot \beta_t]$$

then

$$\text{pref}(P) = \alpha_1 \alpha_2 \dots \alpha_t.$$

Next we will characterize valid $LR(k)$ -items with respect to such a path P where the end node of P is reducible or readable; i.e., $\beta_t = \varepsilon$ or $\beta_t = a\beta'_t$ where $a \in \Sigma$ and $\beta'_t \in V^*$. Let $[B \rightarrow \alpha \cdot C\beta]$, $C \in N$, $\beta \in V^*$ be an item. Then we call β the *right side* of the item $[B \rightarrow \alpha \cdot C\beta]$. The *right side* of an item $[B \rightarrow \alpha \cdot a\beta]$,

$a \in \Sigma, \beta \in V^*$ is $a\beta$. We obtain the *relevant suffix* $suf(P)$ with respect to P by concatenating the right sides from the end node to the start node of P ; i.e.,

$$suf(P) = \begin{cases} \beta_{t-1}\beta_{t-2}\dots\beta_1 & \text{if } \beta_t = \varepsilon \\ a\beta'_t\beta_{t-1}\beta_{t-2}\dots\beta_1 & \text{if } \beta_t = a\beta'_t. \end{cases}$$

Let u be the current lookahead. The $LR(k)$ -item $[A_t \rightarrow \alpha_t \cdot \beta_t, u]$ is *valid for the path* P iff $u \in FIRST_k(suf(P))$.

For an application of Theorem 1 to M_G it would be useful if all maximal viable prefixes of a path corresponding to any current stack would be the same. Let us assume for a moment that this would be the case. Then we can incorporate Theorem 1 into the pushdown automaton M_G . We call the resulting pushdown automaton $LR(k)-M_G$. During the deterministic simulation of $LR(k)-M_G$ the following invariant will be fulfilled:

1. Immediately before an expansion step, all end nodes of the graph \mathcal{G} are of the form $[A \rightarrow \alpha \cdot B\beta]$ or $[A \rightarrow \alpha \cdot a\beta]$ where $\alpha, \beta \in V^*, B \in N$ and $a \in \Sigma$ is the next unread symbol of the input.
2. Immediately before a reduction/reading step, all end nodes of \mathcal{G} are of the form $[A \rightarrow \cdot]$ or $[A \rightarrow \alpha \cdot a\beta]$ where $\alpha, \beta \in V^*$ and $a \in \Sigma$ is the next unread symbol of the input.

Before the first expansion step, the only node of \mathcal{G} is the start node $[S' \rightarrow \cdot S]$. Hence, the invariant is fulfilled before the first expansion step. Assume that the invariant is fulfilled before the current expansion step. Let a be the next unread symbol of the input. Since an alternative $\alpha \in (\Sigma \setminus \{a\})V^*$ cannot lead to an accepting computation, all possible expansions are performed under the restriction that only alternatives in $NV^* \cup \{a\}V^* \cup \{\varepsilon\}$ are used. If a variable C of an end node $[B \rightarrow \alpha \cdot C\beta]$ has only alternatives in $(\Sigma \setminus \{a\})V^*$ then this end node cannot lead to an accepting computation. Hence, such an end node is deleted. Then, a *graph adjustment* is performed; i.e., as long as there is a node where all its successors are removed from the graph \mathcal{G} this node is deleted, too. Obviously, the invariant is fulfilled after the expansion step and hence, before the next reduction/reading step.

Assume that the invariant is fulfilled before the current reduction/reading step. Let u be the current lookahead. Three cases can arise:

Case 1: There is a path P from the start node to an end node $[A \rightarrow \cdot]$ such that the $LR(k)$ -item $[A \rightarrow \cdot, u]$ is valid for P .

Then according to Theorem 1, the corresponding reduction is the unique step performed by the parser. Hence, all other end nodes of the graph \mathcal{G} are deleted. Then, a graph adjustment and the reduction with respect to the end node $[A \rightarrow \cdot]$ are performed. For each direct predecessor u of the node $[A \rightarrow \cdot]$ which has Type 1, we move the dot of the item u one position to the right. If u is of Type 2 then we copy u and all ingoing edges and move the dot of the copy u' one position to the right. The resulting items are the new end nodes of the graph and are of the form $[B \rightarrow \alpha A \cdot \beta]$ where $\beta \in V^*$. If $\beta \in NV^*$ then

the item $[B \rightarrow \alpha A \cdot \beta]$ is expansible. If $\beta = \varepsilon$ then the resulting item $[B \rightarrow \alpha A \cdot]$ is reducible. If the $LR(k)$ -item $[B \rightarrow \alpha A \cdot, u]$ is valid then the reduction with respect to the end node $[B \rightarrow \alpha A \cdot]$ is performed. Since after the expansion of any expansible end node each constructed reducible end node would be of the form $[C \rightarrow \cdot]$, by Theorem 1, all constructed end nodes cannot lead to a valid $LR(k)$ -item. Hence, we need not perform the expansion of any expansible end node if the reduction of the end node $[B \rightarrow \alpha A \cdot]$ is performed such that all other end nodes are deleted from the graph. If the $LR(k)$ -item $[B \rightarrow \alpha A \cdot, u]$ is not valid then the end node $[B \rightarrow \alpha A \cdot]$ is deleted. If $\beta \in (\Sigma \setminus \{a\})V^*$ then this end node cannot lead to an accepting computation and can be deleted from the graph. Then, a graph adjustment is performed. Hence, after the reduction step, all end nodes are of the form $[B \rightarrow \alpha A \cdot \beta]$ with $\beta \in NV^* \cup \{a\}V^*$. Therefore, the invariant is fulfilled before the next step.

Case 2: There is no such a path P but there is at least one end node with the terminal symbol a behind the dot.

Then, the corresponding reading step is the only possible step performed by the parser. All end nodes which do not correspond to this reading step are removed from the graph followed by a graph adjustment. Then we perform the reading step with respect to all remaining end nodes. This means that the next input symbol a is read and the dot is moved one position to the right with respect to all end nodes. Then the resulting items are of the form $[B \rightarrow \alpha a \cdot \beta]$ where $\beta \in V^*$. Let a' be the next unread input symbol and u' be the current lookahead. The same discussion as above shows that after the termination of the current reduction/reading step all end nodes are of the form $[B \rightarrow \alpha a \cdot \beta]$ with $\beta \in NV^* \cup \{a'\}V^*$. Hence, the invariant is fulfilled before the next step.

Case 3: If none of the two cases described above is fulfilled.

Then, the $LR(k)$ -grammar G does not generate the input.

The following lemma shows that the same maximal viable prefix corresponds to all paths from the start node to an end node in \mathcal{G} . Hence, Theorem 1 can be applied during each reduction/reading step.

Lemma 2 *Let $G = (V, \Sigma, P, S)$ be an $LR(k)$ -grammar and let $\mathcal{G} = (V, \mathcal{E})$ be the graph constructed by the deterministic simulation of $LR(k)$ - M_G . Then at any time for any two paths P and Q from the start node $[S' \rightarrow \cdot S]$ to any end node it holds $pref(P) = pref(Q)$.*

Proof: We prove the lemma by induction on the number of performed reductions and readings. At the beginning, the only node of the graph is the start node $[S' \rightarrow \cdot S]$. An expansion does not change the maximal viable prefix with respect to any path since the left side of any corresponding item is ε . Hence, after the first round of the first subphase, ε is the unique maximal viable prefix of all paths from the start to an end node of \mathcal{G} . This implies that the assertion holds before the first reduction or reading.

Assume that the assertion is fulfilled after l , $l \geq 0$, reductions/readings. The expansions performed between the l th and the $(l + 1)$ th reduction/reading do

not change the maximal viable prefix of any path from the start to an end node of \mathcal{G} . Hence, the assertion is fulfilled immediately before the $(l + 1)$ th reduction/reading. Let γ be the unique maximal viable prefix which corresponds to all paths from the start to an end node of the graph \mathcal{G} . Let y be the unread suffix of the input. Two cases can arise:

Case 1: A reduction is applicable.

Then the maximal viable prefix γ has the form $\gamma = \alpha\beta$ such that there is an $LR(k)$ -item $[A \rightarrow \beta \cdot, FIRST_k(y)]$ which is valid with respect to a path P from the start node to an end node $[A \rightarrow \beta \cdot]$. Theorem 1 implies that no other $LR(k)$ -item $[C \rightarrow \beta_1 \cdot \beta_2, v]$ with $\beta_2 \in \Sigma V^* \cup \{\varepsilon\}$ is valid for γ . Hence, no other reduction and no reading is applicable. All end nodes which are not consistent with the only applicable reduction are deleted from the graph. As long as there is a node such that all its successors are removed from the graph this node is deleted, too. For the remaining end node $[A \rightarrow \beta \cdot]$ the reduction is performed. This implies that the maximal viable prefix of all corresponding paths from the start to an end node of \mathcal{G} is αA . Altogether, after the $(l + 1)$ th reduction/reading all paths from the start to an end node have the maximal viable prefix αA .

Case 2: No reduction is applicable.

Let $y = ay'$ where $a \in \Sigma$, $y' \in \Sigma^*$. If $\mathcal{V} = \emptyset$ then the input is not in the language generated by the $LR(k)$ -grammar G . Otherwise, all end nodes of the current graph \mathcal{G} have the terminal symbol a behind the dot. Moreover, all paths from the start node to an end node have the maximal viable prefix γ . We perform with respect to all end nodes of the current graph the reading of the next unread input symbol. That is the dot is moved one position to the right behind a . After doing this, all paths from the start node to an end node have the maximal viable prefix γa .

Altogether, after the $(l + 1)$ th reduction/reading, the assertion is fulfilled. ■

7 The implementation of the simulation of $LR(k)$ - M_G

How to realize the implementation of the simulation of $LR(k)$ - M_G described above? Mainly, the following questions arise:

1. How to perform the expansions efficiently?
2. How to perform a reduction/reading step efficiently?

Let i be the index of the current phase and a be the next unread input symbol. Assume that $\gamma_1, \gamma_2, \dots, \gamma_q$ are those alternatives of the variable A which are in $NV^* \cup \{a\}V^* \cup \{\varepsilon\}$. The expansion of an end node $[C \rightarrow \alpha \cdot A\beta]_i$ of the current graph \mathcal{G} is performed in the following way:

- (1) If the variable A is expanded during the current phase for the first time then add the nodes $[A \rightarrow \gamma_j]_i$, $1 \leq j \leq q$ to the current graph \mathcal{G} .
- (2) Add the edges $([C \rightarrow \alpha \cdot A\beta]_i, [A \rightarrow \gamma_j]_i)$, $1 \leq j \leq q$ to the current graph \mathcal{G} .

If the variable A is expanded for the first time then q nodes and q edges are added to the graph. If after this expansion another end node $[C' \rightarrow \alpha' \cdot A\beta']_i$ has to be expanded we would add the q edges $([C' \rightarrow \alpha' \cdot A\beta']_i, [A \rightarrow \cdot \gamma_j]_i)$ to the graph. Therefore, the number of nodes of the graph \mathcal{G} is bounded by $O(|G|n)$ but the number of edges can increase to $O(|G|^2n)$. Hence, our goal is to reduce the number of edges in \mathcal{G} . The idea is to create an additional node A and the edges $(A, [A \rightarrow \cdot \gamma_j]_i)$, $1 \leq j \leq q$. Then, the expansion of an end node $[C \rightarrow \alpha \cdot A\beta]_i$ of the current graph \mathcal{G} can be performed in the following way:

- (1) If the variable A is expanded during the current phase for the first time then add the nodes A and $[A \rightarrow \gamma_j]_i$, $1 \leq j \leq q$ and the edges $(A, [A \rightarrow \cdot \gamma_j]_i)$, $1 \leq j \leq q$ to the current graph \mathcal{G} .
- (2) Add the edge $([C \rightarrow \alpha \cdot A\beta]_i, A)$ to the current graph \mathcal{G} .

Then $q + 1$ edges are inserted for the first expansion of the variable A . For each further expansion of A during the current phase only one edge is inserted. This will lead to an $O(|G|n)$ upper bound for the number of edges in \mathcal{G} . The expansion step transforms the graph \mathcal{G} to a graph \mathcal{G}' .

After the expansion step, a reduction/reading step has to be performed. Let u be the current lookahead. First, we check if there is a path P from the start node to an end node $[A \rightarrow \cdot]$ or $[A \rightarrow \alpha \cdot a\beta]$ such that the $LR(k)$ -item $[A \rightarrow \cdot, u]$ and $[A \rightarrow \alpha \cdot a\beta, u]$, respectively is valid for P . We call such a path P *suitable* for the end node $[A \rightarrow \cdot]$ and $[A \rightarrow \alpha \cdot a\beta]$, respectively. For doing this, we need an answer to the following question:

- Given such an end node $[A \rightarrow \cdot]$ or $[A \rightarrow \alpha \cdot a\beta]$ and a path P from the start node to this end node, how to decide efficiently if $u \in \text{FIRST}_k(\text{suf}(P))$?

The complexity of the reduction/reading step mainly depends on the length k of the lookahead u . First, we will describe the implementation of the reduction/reading step for small k and then for large k .

7.1 Lookaheads of small size

We will consider the most simple case $k = 1$ first and then larger small lengths. Let $k = 1$. We distinguish two cases:

Case 1: There is an end node of the form $[A \rightarrow \alpha \cdot a\beta]$ where $\alpha, \beta \in V^*$ and $a \in \Sigma$.

According to the invariant which is fulfilled during the simulation of $LR(k)$ - M_G , the terminal symbol a is the next unread symbol of the input. Obviously, $a \in \text{FIRST}_1(\text{suf}(P))$ for all paths P from the start node to the end node $[A \rightarrow \alpha \cdot a\beta]$. Hence, the $LR(k)$ -item $[A \rightarrow \alpha \cdot a\beta, a]$ is valid for all such paths. Theorem 1 implies that no $LR(k)$ -item which does not correspond to reading the next input symbol can be valid for a path from the start node to an end node.

Case 2: All end nodes of \mathcal{G}' are of the form $[A \rightarrow \cdot]$.

Let P be a path from the start node to the end node $[A \rightarrow \cdot]$ and let $\text{suf}(P) = A_1A_2 \dots A_r$. Then $A_i \in V$, $1 \leq i \leq r$. The $LR(k)$ -item $[A \rightarrow \cdot, a]$ is valid for P iff $a \in \text{FIRST}_1(A_1A_2 \dots A_r)$. Note that $a \in \text{FIRST}_1(A_1A_2 \dots A_r)$ iff $a \in \text{FIRST}_1(A_1)$ or $\varepsilon \in \text{FIRST}_1(A_1)$ and $a \in \text{FIRST}_1(A_2A_3 \dots A_r)$. Hence, $a \in \text{FIRST}_1(\text{suf}(P))$ iff there is $1 \leq i \leq r$ such that $\varepsilon \in \text{FIRST}_1(A_1A_2 \dots A_{i-1})$ and $a \in \text{FIRST}_1(A_i)$. For the decision if $a \in \text{FIRST}_1(\text{suf}(P))$, we consider $A_1A_2 \dots A_r$ from left to right. Assume that A_j is the current considered symbol. If $a \in \text{FIRST}_1(A_j)$ then $a \in \text{FIRST}_1(\text{suf}(P))$. Otherwise, if $\varepsilon \notin \text{FIRST}_1(A_j)$ or $j = r$ then $a \notin \text{FIRST}_1(\text{suf}(P))$. If $\varepsilon \in \text{FIRST}_1(A_j)$ and $j < r$ then the next symbol A_{j+1} of $\text{suf}(P)$ is considered.

Now we know how to decide if the current lookahead a is contained in $\text{FIRST}_1(\text{suf}(P))$ for a given path P from the start node to a readable or reducible end node. But we have to solve the following more general problem:

- Given an end node $[A \rightarrow \alpha \cdot a\beta]$ or $[A \rightarrow \cdot]$, how to decide if there is a path P from the start node to this end node with $a \in \text{FIRST}_1(\text{suf}(P))$?

The first case is trivial since for all paths P from the start node to the end node $[A \rightarrow \alpha \cdot a\beta]$ there holds $a \in \text{FIRST}_1(\text{suf}(P))$. In the second case, there can be a large number of paths from the start node to the end node $[A \rightarrow \cdot]$ such that we cannot answer this question by checking each such a path separately. Hence, we check all such paths simultaneously. The idea is to apply an appropriate graph search method to \mathcal{G}' .

A *topological search* on a directed graph is a search which visits only nodes with the property that all its predecessors are already visited. A *reversed search* on a directed graph is a search on the graph where the edges are traversed against their direction. A *reversed topological search* on a directed graph is a reversed search which visits only nodes where all its successors are already visited. Note that topological search and reversed topological search can only be applied to acyclic graphs.

It is useful to analyze the structure of the graph $\mathcal{G}(A)$ which is constructed according the expansion of the variable A . The graph $\mathcal{G}(A)$ depends only on the grammar and not on the current input of the parser. Note that $\mathcal{G}(A)$ has the unique start node A . The nodes without successors are the end nodes of $\mathcal{G}(A)$. An expansion step only inserts nodes where the left side of the corresponding item is ε . A successor $[C \rightarrow \cdot A\beta]$ of the start node A in $\mathcal{G}(A)$ is called *final node* of $\mathcal{G}(A)$. Observe that $([C \rightarrow \cdot A\beta], A)$ is an edge which closes a cycle in $\mathcal{G}(A)$. We call such an edge *closing edge*. Such cycles formed by closing edges are the only cycles in \mathcal{G}' .

The idea is to perform a reversed topological search on \mathcal{G}' although \mathcal{G}' is not acyclic. The following questions have to be answered:

1. What is the information which has to be transported through the graph during the search?
2. How to treat the cycles in \mathcal{G}' during the reversed topological search?

At the beginning of the reversed topological search, the only nodes where all successors are already visited are the end nodes of \mathcal{G}' . Hence, the search starts with an end node. If the graph \mathcal{G}' contains a readable end node then the search starts with a readable end node. Otherwise, the search starts with a reducible end node. We discuss both cases one after the other.

Case 1: There exists a readable end node.

Then $a \in FIRST_1(suf(P))$ for all paths P from the start node to a readable end node. All reducible end nodes are deleted from the graph. As long as there is a node such that all its successors are removed from the graph this node is deleted, too. In all remaining end nodes the dot is moved one position to the right. This terminates the current phase.

Case 2: There exists no readable end node.

Assume that the search starts with the end node $[A \rightarrow \cdot]$. Then a has to be derived from right sides of items which correspond to predecessors of the node $[A \rightarrow \cdot]$. This information associated with the end node $[A \rightarrow \cdot]$ has to be transported to its direct predecessor A .

Nodes which correspond to an item have outdegree zero or one. Only nodes which correspond to a variable C can have outdegree larger than one. If one visit the node C during the backward topological search then we know that there is a path Q with start node C such that $\varepsilon \in FIRST_1(suf(Q))$. If the node C would be visited over two different outgoing edges of C then there would exist at least two different such paths Q and Q' . Since all paths from the start node of \mathcal{G}' to an end node have the same maximal viable prefix it follows that $pref(Q) = pref(Q')$. Hence, there would be a word in $L(G)$ having at least two different leftmost derivations. Since $LR(k)$ -grammars are unambiguous this cannot happen. Therefore, such a node C can only be visited over one of its outgoing edges during the reversed topological search.

Assume that we enter the node C over an outgoing edge e and there is a closing edge $([B \rightarrow \cdot C\gamma], C)$. Before the continuation of the reversed topological search at the node C , the search is continued at the node $[B \rightarrow \cdot C\gamma]$. Note that this node is a successor of the node C in the graph \mathcal{G}' . But it cannot happen that we visit the node C again since this would imply that the grammar has to be ambiguous. Hence, either one finds a path P such that $a \in FIRST_1(suf(P))$ or one detects that no such a path using the cycle exists before reaching the node C again. This observation implies that, although the graph \mathcal{G}' may contain some cycles, for the reversed topological search the graph can be considered as an acyclic graph. After the treatment of all closing edges with end node C , the reversed topological search is continued at the node C .

Let P_0 be a path from the start node to the end node $[A \rightarrow \cdot]$ in \mathcal{G}' with $a \in FIRST_1(suf(P))$. It is worth to investigate the structure of P_0 . Let

$$P_0 = [S' \rightarrow \cdot S], \dots, [C_t \rightarrow \cdot C_{t-1}\gamma_t], \dots, [C_2 \rightarrow \cdot C_1\gamma_2], [C_1 \rightarrow \cdot A\gamma_1], [A \rightarrow \cdot]$$

where $\gamma_i \in N^*$, $\varepsilon \in FIRST_1(\gamma_i)$, $a \notin FIRST_1(\gamma_i)$ for $1 \leq i \leq t-1$ and $a \in FIRST_1(\gamma_t)$. After the reduction of the end node $[A \rightarrow \cdot]$, we obtain from

P_0 the path

$$P_1 = [S' \rightarrow \cdot S], \dots, [C_t \rightarrow \cdot C_{t-1} \gamma_t], \dots, [C_2 \rightarrow \cdot C_1 \gamma_2], [C_1 \rightarrow A \cdot \gamma_1]$$

Then ε is derived from γ_1 . Since $LR(k)$ -grammars are unambiguous, there is a unique derivation of ε from γ_1 . After the performance of all corresponding expansions and reductions, we obtain from P_1 the path

$$P_2 = [S' \rightarrow \cdot S], \dots, [C_t \rightarrow \cdot C_{t-1} \gamma_t], \dots, [C_2 \rightarrow \cdot C_1 \gamma_2], [C_1 \rightarrow A \gamma_1 \cdot].$$

Then, the end node $[C_1 \rightarrow A \gamma_1 \cdot]$ is reduced obtaining the path

$$P_3 = [S' \rightarrow \cdot S], \dots, [C_t \rightarrow \cdot C_{t-1} \gamma_t], \dots, [C_2 \rightarrow C_1 \cdot \gamma_2].$$

This kind of derivations is continued obtaining the path

$$P_{t-1} = [S' \rightarrow \cdot S], \dots, [C_t \rightarrow C_{t-1} \cdot \gamma_t].$$

Theorem 1 implies that all these expansions and reductions are performed with respect to all paths which are suitable for the end node $[A \rightarrow \cdot]$ in \mathcal{G}' . Hence, it is easy to prove by induction that each path P from the start node to $[A \rightarrow \cdot]$ with $a \in \text{FIRST}_1(\text{suf}(P))$ in \mathcal{G}' can be written as $P = P'Q$, where

$$Q = [C_{t-1} \rightarrow \cdot C_{t-2} \gamma_{t-1}], \dots, [C_2 \rightarrow \cdot C_1 \gamma_2], [C_1 \rightarrow A \gamma_1], [A \rightarrow \cdot].$$

After performing the expansions and reductions with respect to the path Q in the graph \mathcal{G}' we obtain a graph \mathcal{G}_1 which contains for each such a path $P = P'Q$ the path P'' , where P'' is obtained from P' by moving the dot in the last node of P' one position to the right. The path P_{t-1} is obtained from the path P_0 . Note that $[C_t \rightarrow C_{t-1} \cdot \gamma_t]$ is an end node of \mathcal{G}_1 . Now, an expansion step is performed. The expansion step transforms the graph \mathcal{G}_1 to a graph \mathcal{G}'_1 . Two subcases are possible:

Case 2.1: There is an end node $[A' \rightarrow \cdot]$ with \mathcal{G}'_1 contains a path which is suitable for $[A' \rightarrow \cdot]$.

Theorem 1 implies that $[A' \rightarrow \cdot]$ is the unique end node for which a suitable path in \mathcal{G}'_1 exists. The same consideration as above shows that there is a path Q' such that each path P'' in \mathcal{G}'_1 which is suitable for $[A' \rightarrow \cdot]$ can be written as $P'' = RQ'$. Note that for different such paths P'' , the paths R can be different. After performing the expansions and reductions with respect to the path Q' in the graph \mathcal{G}'_1 we obtain a graph \mathcal{G}_2 , and so on.

Case 2.2: There is no end node $[A' \rightarrow \cdot]$ with \mathcal{G}'_1 contains a path which is suitable for $[A' \rightarrow \cdot]$.

Then there is at least one readable end node and the readable end nodes are exactly the end nodes for which the graph \mathcal{G}' contains a suitable path. Then we are in Case 1.

Next we will analyze the used time and space of the simulation of $LR(k)$ - M_G . Let $ld(\text{input})$ denote the length of the derivation of the input. The insertion and

the deletion of all nodes and edges which correspond to reductions performed during the simulation of $LR(k)$ - M_G can be counted against the corresponding production in the derivation of the input. We have shown that with respect to all paths from the start node to an end node in the current graph, the same reductions have been performed. Hence, the total time used for such nodes and edges is $O(ld(input))$. Besides these nodes and edges, $O(|G|)$ nodes and edges are inserted during a phase. Hence, the total time used for all expansions which do not correspond to reductions is bounded by $O(n|G|)$. During a reversed topological search, the time used for the visit of a node or an edge is zero or constant. If during the search a node is visited, the node takes part on an expansion, is deleted or its dot is moved one position to the right. Hence, the total time used for nodes and edges during a reversed topological search which do not correspond to a reduction is bounded by $O(n|G|)$.

During the reversed topological searches we have to decide if ε or the next unread input symbol a is contained in $FIRST_1(A_j)$ where $A_j \in V$. This is trivial for $A_j \in \Sigma$. For $A_j \in N$ we need a representation of $FIRST_1(A_j)$. A possible representation is an array of size $|\Sigma| + 1$ such that each decision can be made in constant time. Then, we need for each variable in N an additional space of size $O(|\Sigma|)$. Altogether, we have proved the following theorem:

Theorem 2 *Let $G = (V, \Sigma, P, S)$ be an $LR(1)$ -grammar. Let $ld(input)$ denote the length of the derivation of the input. Then there is an extended $LR(1)$ -parser P_G for G which has the following properties:*

- i) The size of the parser is $O(|G| + |N||\Sigma|)$.*
- ii) P_G needs only the additional space for the manipulation of a directed graph of size $O(|G|n)$ where n is the length of the input.*
- iii) The parsing time is bounded by $O(ld(input) + |G|n)$.*

Next, we will extend the solution developed for $k = 1$ to larger k . A lookahead $u := x_1x_2 \dots x_k$ of length k has k proper prefixes $\varepsilon, x_1, x_1x_2, \dots, x_1x_2 \dots x_{k-1}$. Let P be a path from the start node of \mathcal{G} to an end node $[A \rightarrow \cdot]$ or $[A \rightarrow \alpha \cdot a\beta]$ and let $suf(P) = A_1A_2 \dots A_r$. Note that $u \in FIRST_k(A_1A_2 \dots A_r)$ iff for all $1 < i \leq r$ there is $u \in FIRST_k(A_1A_2 \dots A_{i-1})$ or there is a proper prefix u' of u such that $u' \in FIRST_k(A_1A_2 \dots A_{i-1})$ and $u'' \in FIRST_k(A_iA_{i+1} \dots A_r)$ where $u = u'u''$. For the decision if $u \in FIRST_k(suf(P))$ we consider $A_1A_2 \dots A_r$ from left to right. Assume that A_j is the current considered symbol. If $j = 1$ then we have to compute all prefixes of u which are contained in $FIRST_k(A_1)$. If no such a prefix exists then $u \notin FIRST_k(A_1A_2 \dots A_r)$. Assume that $j > 1$. Let $U := \{u'_1, u'_2, \dots, u'_s\} \neq \emptyset$ be the set of proper prefixes of u which are contained in $FIRST_k(A_1A_2 \dots A_{j-1})$. For $1 \leq i \leq s$ let $u = u'_i u''_i$. We have to compute all prefixes of u''_i which are contained in $FIRST_k(A_j)$. If no prefix of u''_i is contained in $FIRST_k(A_j)$ then u'_i cannot be extended to the lookahead u with respect to $FIRST_k(A_1A_2 \dots A_r)$ and needs no further consideration. Then the prefixes of u contained in $FIRST_k(A_1A_2 \dots A_j)$ are obtained by the concatenation of u'_i and all prefixes of u''_i in $FIRST_k(A_j)$ for $1 \leq i \leq s$.

For the decision if there is an end node of \mathcal{G} such that there is a path P from the start node to this end node with $u \in FIRST_k(suf(P))$, a reversed

topological search on \mathcal{G}' is performed. Since the length of the lookahead is larger than one, a graph search has also to be performed with respect to readable end nodes. Furthermore, we have to transport from a node v to its predecessors a list of proper prefixes of u where each prefix is associated with a unique reducible or readable end node. For a node v we denote its list of prefixes of u by $L(v)$. A proper prefix u' of u associated with an end node w is contained in the list iff there is a path Q from v to w such that $u' \in \text{FIRST}_k(\text{suf}(Q))$. Only nodes which correspond to variables have outdegree larger than one. For such nodes we obtain one list by the union of the lists corresponding to its direct successors. Since $LR(k)$ -grammars are unambiguous, the same proper prefix of u is not contained in two different lists with respect to the direct successors of a node. Assume that we enter the node C over an outgoing edge e and there is a closing edge $([B \rightarrow \cdot C\gamma], C)$. Before the continuation of the reversed topological search at the node C , the list $L(C)$ has to be transported to the node $[B \rightarrow \cdot C\gamma]$ and the search is continued at the node $[B \rightarrow \cdot C\gamma]$. Note that this node is a successor of the node C in the graph \mathcal{G}' . But it cannot happen that we visit the node C again with a prefix u' of u which is already contained in the list $L(C)$. Otherwise, the grammar would be ambiguous. Hence, the node C can only be reentered with prefixes of u which are not already in the list. During the last run through the cycle, either one finds a path P such that $u \in \text{FIRST}_1(\text{suf}(P))$ or one detects that no such a path using the cycle again exists before reaching the node C . Hence, the number of continuations of the reversed topological search at the node $[B \rightarrow \cdot C\gamma]$ is bounded by $k-1$. This observation implies that, although the graph \mathcal{G}' may contain some cycles, for the reversed topological search, the graph can be considered as an acyclic graph. After the treatment of all outgoing edges of the node C and all closing edges with end node C , the final list $L(C)$ is computed. Then, the reversed topological search is continued at the node C .

Assume that during a reversed topological search, the symbol $A_j \in V$ is considered and that $U = \{u'_1, u'_2, \dots, u'_s\}$ is the set of proper prefixes of the current lookahead u which belongs to this consideration. This means that for all $1 \leq i \leq s$ there is a path Q_i from the point under consideration in the graph to an end node such that $u'_i \in \text{FIRST}_k(\text{suf}(Q_i))$. For $1 \leq i \leq s$ let $u = u'_i u''_i$. We have to compute all prefixes of u which are contained in $\text{FIRST}_k(\text{suf}(Q_i)A_j)$ for any $1 \leq i \leq s$. Let U' denote the set of these prefixes. A prefix \bar{u} of u is contained in U' iff there exists $1 \leq i \leq s$ such that

1. $\bar{u} = u'_i \bar{u}_i$ and $\bar{u}_i \in \text{FIRST}_k(A_j)$, or
2. $\bar{u} = u'_i \bar{u}_i = u$ and \bar{u}_i is prefix of an element in $\text{FIRST}_k(A_j)$.

Since $LR(k)$ -grammars are unambiguous, for all $\bar{u} \in U'$ there is exactly one $i \in \{1, 2, \dots, s\}$ such that $\bar{u} \in \text{FIRST}_k(\text{suf}(Q_i)A_j)$. Note that all information needed for the computation of U' depends only on the lookahead u , the set U and $\text{FIRST}_k(A_j)$. Hence, in dependence on all possible u , U and A_j , we can precompute the corresponding sets U' .

Instead of storing the elements of U we can store the lengths of these prefixes. This can be realized by a binary vector of length k . The i -th component of the

vector is one iff the prefix of length $i - 1$ is in U . Let $v(U)$ denote the vector corresponding to the list U of prefixes of u . With respect to each component of the vector with value one, we have to specify the unique end node of the graph associated with the corresponding proper prefix of u . If we number the possible end nodes then at most $O(\log |G|)$ bits are needed for each specification.

We can represent the set of vectors corresponding to all possible U' by a table where in dependence of the current lookahead u , the current $v(U)$ and the symbol $A_j \in V$ under consideration we get the vector $v(U')$. For each component i in $v(U')$ which has the value one we need the specification of the component l such that $x_1x_2 \dots x_l \in U$ and $x_{l+1}x_{l+2} \dots x_i \in \text{FIRST}_k(A_j)$ or $x_{l+1}x_{l+2} \dots x_i$ is a prefix of an element in $\text{FIRST}_k(A_j)$ in the case $i = k$. Then, the end node corresponding to $x_1x_2 \dots x_l$ in U is the end node which corresponds to $x_1x_2 \dots x_i$ in U' . Let $\#LA$ denote the number of the possible lookaheads with respect to the $LR(k)$ -grammar G . Obviously, $\#LA \leq |\Sigma|^k$. Then, the size of the table above is $O(\#LA|V|2^k k \log k)$. If $A_j \in \Sigma$ then U' can easily be computed from U in $O(k)$ time. This would reduce the size of the table to $O(\#LA|N|2^k k \log k)$. During the reversed topological search, the time used for the visit of a node or an edge is $O(k)$. Hence, the used time increases to $O(\text{ld}(\text{input}) + k|G|n)$. Altogether, we have proved the following theorem:

Theorem 3 *Let $G = (V, \Sigma, P, S)$ be an $LR(k)$ -grammar. Let $\#LA$ denote the number of possible lookaheads of length k with respect to G and let $\text{ld}(\text{input})$ denote the length of the derivation of the input. Then there is an extended $LR(k)$ -parser P_G for G which has the following properties:*

- i) The size of the parser is $O(|G| + \#LA|N|2^k k \log k)$.*
- ii) P_G needs only the additional space for the manipulation of a directed graph of size $O(|G|n)$ where n is the length of the input.*
- iii) The parsing time is bounded by $O(\text{ld}(\text{input}) + k|G|n)$.*

7.2 Lookaheads of large size

If the size k of the lookahead is large then the size $\#LA|N|2^k k \log k$ of the table described in Section 7.1 can be too large. Hence, we describe an implementation of $LR(k)$ - M_G without the precomputation of these tables. For getting an efficient implementation, the parser P_G contains for each variable $X \in N$ the trie $T_k(X)$ which represents the set $\text{FIRST}_k(X)$. Assume that during a reversed topological search, the symbol $A_j \in V$ is considered and that $U = \{u'_1, u'_2, \dots, u'_s\}$ is the set of proper prefixes of the current lookahead $u := x_1x_2 \dots x_k$ which belongs to this consideration. This means that for all $1 \leq i \leq s$ there is a path Q_i from the point under consideration in the graph to an end node such that $u'_i \in \text{FIRST}_k(\text{su}f(Q_i))$. For $1 \leq i \leq s$ let $u = u'_i u''_i$. We have to compute the set U' of all prefixes of u which are contained in $\text{FIRST}_k(\text{su}f(Q_i)A_j)$ for any $1 \leq i \leq s$. Instead of using a precomputed table, the parser P_G considers iteratively all lengths $|u'_1|, |u'_2|, \dots, |u'_s|$. Let q be the current considered length. Two cases can arise:

Case 1: $A_j \in \Sigma$.

If $A_j = x_{q+1}$ then $FIRST_k(A_1A_2 \dots A_j)$ contains the prefix $x_1 \dots x_{q+1}$ of the lookahead u . Hence, we increase the current considered length q by one. Otherwise, P_G is in a dead end with respect to the prefix of length q of u such that the length q can be deleted with respect to the path P .

Case 2: $A_j \in N$.

Our goal is to determine all prefixes of $u(q) := x_{q+1}x_{q+2} \dots x_k$ which can be derived exactly from A_j . This means that we have to compute all prefixes u'' of $u(q)$ which are also prefix of an element in $FIRST_k(A_j)$. For doing this, P_G starts to read $x_{q+1}x_{q+2} \dots x_k$ and, simultaneously, to follow the corresponding path in $T(A_j)$, starting at the root, until the maximal prefix \tilde{u} of $u(q)$ in $T_k(A_j)$ is determined. If $|\tilde{u}| = k - q$ then $u \in FIRST_k(A_1A_2 \dots A_j)$ and P_G knows that the corresponding $LR(k)$ -item is valid for a path P . If $|\tilde{u}| < k - q$ then we have to derive from A_j a prefix u'' of \tilde{u} . Hence, it is useful if P_G has direct access to all such prefixes. For getting this, every node $v \in T_k(X)$, $X \in N$ contains a pointer to the node $w \in T_k(X)$ such that

- a) $s(w) \in FIRST_k(X)$, and
- b) w is the last node $\neq v$ on the path from the root to v which fulfills a).

For each such a prefix u'' , P_G stores $q + |u''|$. Note that P_G already read $l - q$ of these $k - q$ symbols where l is the length of the prefix of the lookahead already read. We do not want to read these symbols of the input again. Hence, P_G needs the possibility of direct access to the “correct” node in $T_k(A_j)$ with respect to the read prefix of the next $k - q$ symbols. For getting this direct access, we extend P_G by a trie T_G representing the set Σ^k . Moreover, P_G manipulates a pointer $P(T_G)$ which always points to the node r in T_G with $s(r)$ is the prefix of the lookahead u already read. For $v \in T_G$ let $d(v)$ denote the depth of v in T_G and $s_i(v)$, $0 \leq i < d(v)$ denote the suffix of $s(v)$ which starts with the $(i+1)$ th symbol of $s(v)$. Every node $v \in T_G$ contains for all $A \in N$ and $1 \leq i < d(v)$ a pointer $P_{i,A}(v)$ which points to the node $w \in T_k(A)$ such that $s(w)$ is the maximal prefix of an element of $FIRST_k(A)$ which is also a prefix of $s_i(v)$. Using the pointer $P_{q,A_j}(v)$, where v is the node to which $P(T_G)$ points, P_G has direct access to the correct node w in $T_k(A_j)$.

If $s(w) \neq s_q(v)$ then $s(w)$ is the maximal prefix of $s_q(v)$ which is prefix of an element of $FIRST_k(A_j)$. For every prefix u'' of $s(w)$ with $u'' \in FIRST_k(A_j)$, the parser P_G knows that $x_1x_2 \dots x_qx_{q+1}x_{q+2} \dots x_{q+|u''|} \in FIRST_k(A_1A_2 \dots A_j)$. Hence, P_G stores the length $q + |u''|$. If no such u'' exists, then P_G is in a dead end with respect to the length q such that the length q can be deleted from the list.

If $s(w) = s_q(v)$ then P_G continues to read the rest of the lookahead u and, simultaneously, follows the corresponding path in $T_k(A_j)$, starting at the node w . If the whole lookahead u is read and $u \in FIRST_k(A_1A_2 \dots A_j)$ then the process is terminated and P_G knows that the $LR(k)$ -item $[A \rightarrow \cdot, u]$ is valid for a path P . Otherwise, if a proper prefix u'' of u is in $FIRST_k(A_1A_2 \dots A_j)$ then P_G continues the reversed topological search.

Next we want to bound the size of P_G . By construction, P_G contains $|N| + 1$ tries, the trie T_G and the tries $T_k(A)$, $A \in N$. Each trie consists of at most $2|\Sigma|^k$ nodes. Since we only need nodes which correspond to possible lookaheads, this bound reduces to $k\#LA$. Every node in a trie $T_k(A)$, $A \in N$ contains one pointer. Each node in T_G contains for every $A \in N$ at most k pointers which points to a node in $T_k(A)$. Therefore, the total number of pointers in T_G is bounded by $\min\{\#LA|N|k^2, |\Sigma|^k|N|2k\}$. Hence, all tries need $O(\min\{\#LA|N|k^2, |\Sigma|^k|N|k\})$ space. Altogether, we have proved the following theorem:

Theorem 4 *Let $G = (V, \Sigma, P, S)$ be an $LR(k)$ -grammar. Let $\#LA$ denote the number of possible lookaheads of length k with respect to G and let $ld(input)$ denote the length of the derivation of the input. Then there is an extended $LR(k)$ -parser P_G for G which has the following properties:*

- i) The size of the parser is $O(|G| + \min\{\#LA|N|k^2, |\Sigma|^k|N|k\})$.*
- ii) P_G needs only the additional space for the manipulation of a directed graph of size $O(|G|n)$ where n is the length of the input.*
- iii) The parsing time is bounded by $O(ld(input) + k|G|n)$.*

8 Conclusion

We have constructed for $LR(k)$ -grammars extended $LR(k)$ -parsers of polynomial size. Hence, for small sizes of the lookahead (e.g. $k < 10$), $LR(k)$ -grammars can be used instead of $LALR(1)$ -grammars which are mostly used in practice. Moreover, if the number of lookaheads is not too large, $LR(k)$ -grammars can also be used for large sizes of the lookahead. These possibilities open some new research directions, for instance:

1. The construction of parser generators for extended $LR(k)$ -parsers.
2. The development of new concepts for programming languages which use $LR(k)$ -grammars for larger k .
3. The development of parser which use an $LR(k)$ -grammar with small k and another $LR(k)$ -grammar with large k but a small number of possible lookaheads and the construction of parser generators for such combined grammars.
4. The development of new concepts for programming languages which use such combined grammars.
5. The extension of the method to natural languages (see [10]).

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